



Juan José Salazar González
Department of Mathematics, Statistics & Operational Research
Universidad de La Laguna, Tenerife, Canary Islands, Spain
jjsalaza@ull.es
jjsalaza.webs.ull.es

"MOBILITY FOR GROWTH", Safe, integrated and resilient transport systems







## Background of the team

- We are a team of about 10 researchers in Combinatorial Optimization, Mathematical Programming, and Operational Research
- We have published more than 100 articles in journals like "Transportation Science", "Transportation Research", "Computers & Operations Research", etc. www.goma.ull.es
- Universidad de La Laguna (Tenerife) was created in 1701 and currently has around 23.000 students





## **Our experience in Logistics**

- We have investigated vehicle routing problems including time windows, pickup and deliveries, durating constraints, speed optimization, variable capacities, stochastic demands, etc.
- We have collaborated with other teams in Spain, Canada and Italy, and published articles with new models and new (exact and heuristic) algorithms.
- We are authors of chapters in several textbooks.



VEHICLE ROUTING Problems, Methods,

and Applications





## Our contribution in the new call

We have long experience in Logistics, with strong research results on Vehicle Routing and Schedulling.

We can contribute to

\* MG-2-8-2019: Innovative application of drones

For ensuring safety in transport

\* MG-2-9-2019: Integrated multimodal,

low-emission freight transport systems and logistics







## Conclusion

- We have experience in modelling and solving complex problems in logistics, optimizing limited resources.
- We have experience working in international research projects with partners, PhD students, delivering computer codes (software), statistical analysis, and publishing articles in top-level scientific journals.
- We are looking for project proposals where we could contribute with our experience in the topic "MOBILITY FOR GROWTH: Safe, integrated and resilient transport systems"
  - jjsalaza@ull.es

