

Introduction to RobMoSys: Composable Models & Software for Robotics Systems

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RoMoSys in a Nutshell



- **RobMoSys**: Composable Models and Software for Robotic Systems
- In response to **H2020** Project – ICT-26- TOPIC : System abilities, development and pilot installations
- SubTopic c: **Innovation Action** on systems development technology.

The “**System development tools**” sub-call

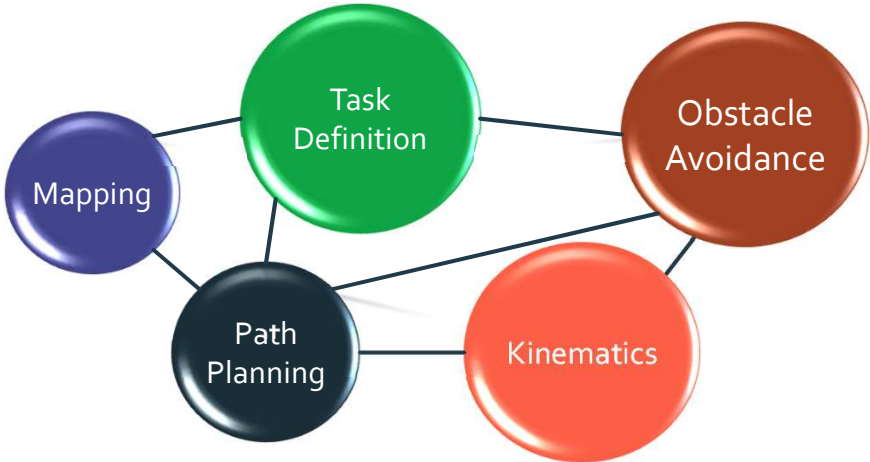
- **Start Date** 01/01/2017
- **End Date** 31/12/2020
- **Duration** 4 Years
- **Budget** 8M, thereof 4 M for Open-Calls
- **Web Site** <https://robmosys.eu>



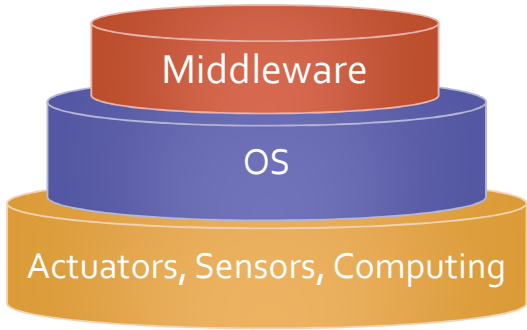
Complexity in SW Robotics



Application



Algorithms



Platforms



Stakeholders

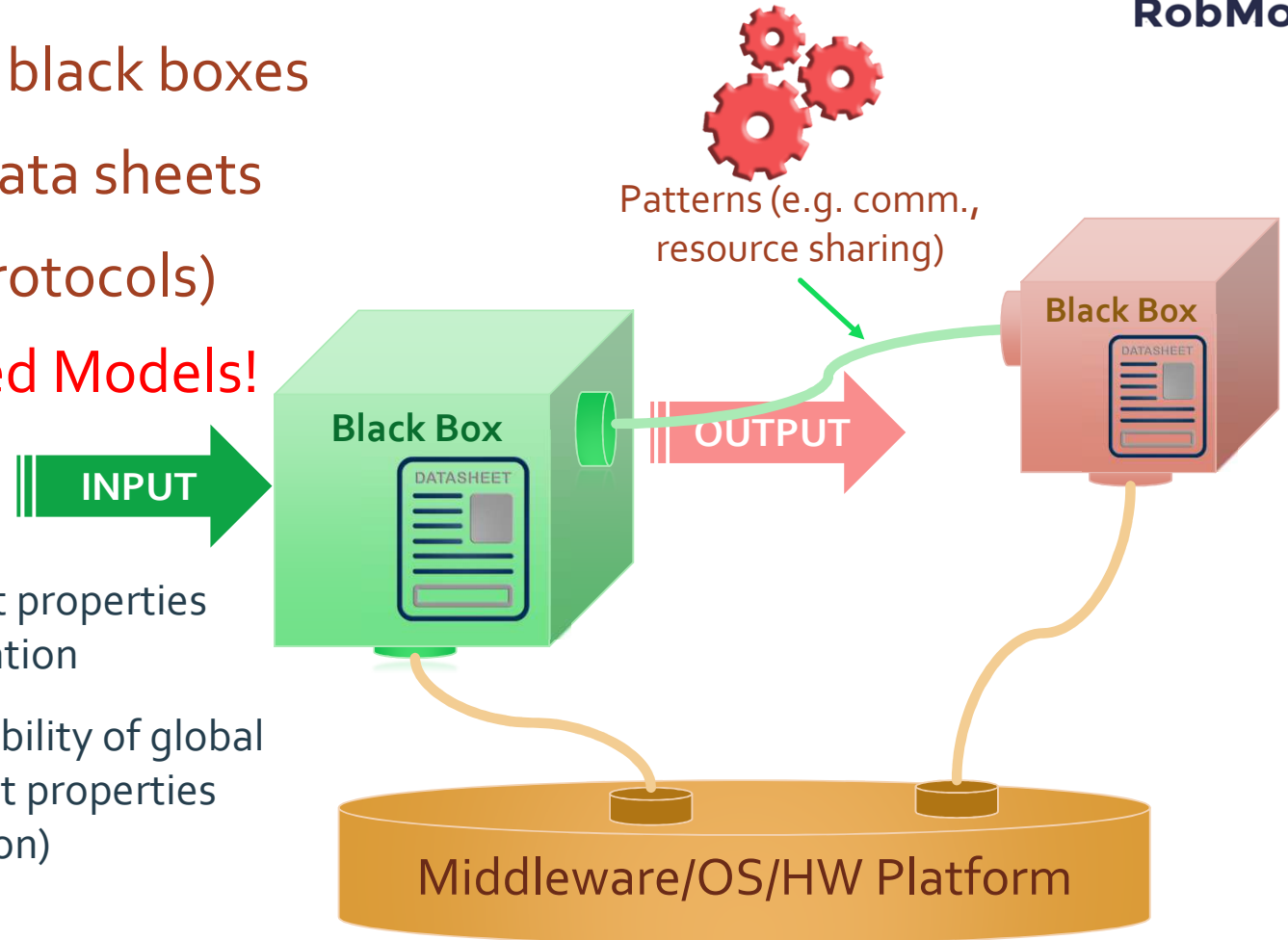
RobMoSys Composition Principles

1. Components as black boxes
2. Interfaces like data sheets
3. Patterns (e.g. protocols)

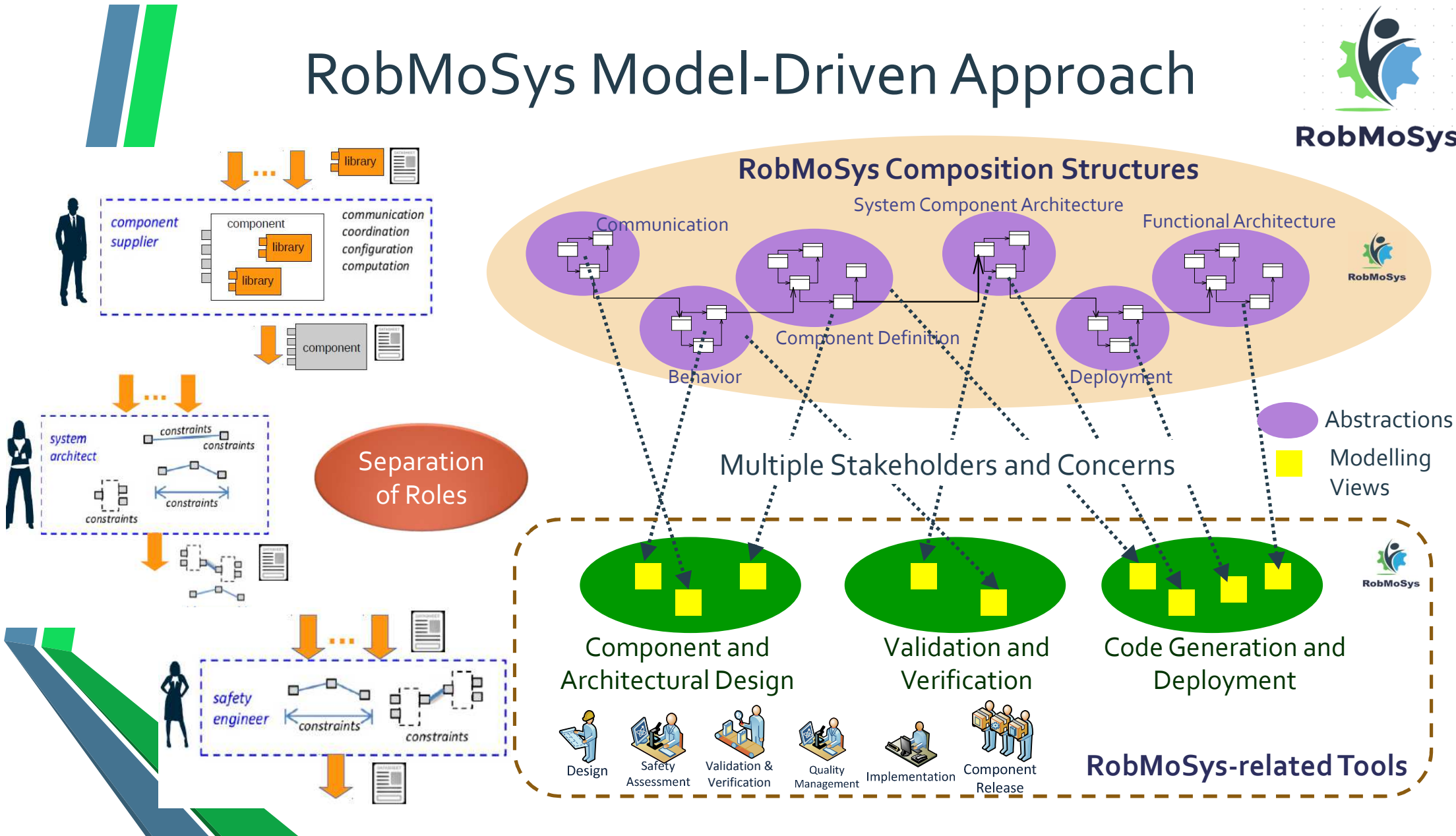
Need of Standardised Models!

Composability: component properties preservation across integration

Compositionality: Predictability of global properties from component properties (correctness-by-construction)



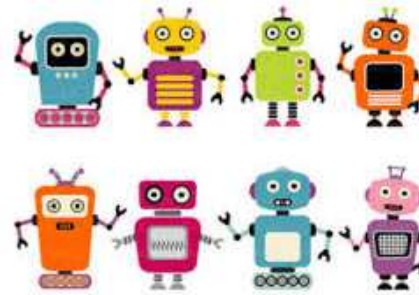
RobMoSys Model-Driven Approach



RobMoSys Roadmap



Better Models,
Software & Tools



Pilots & Success
Stories

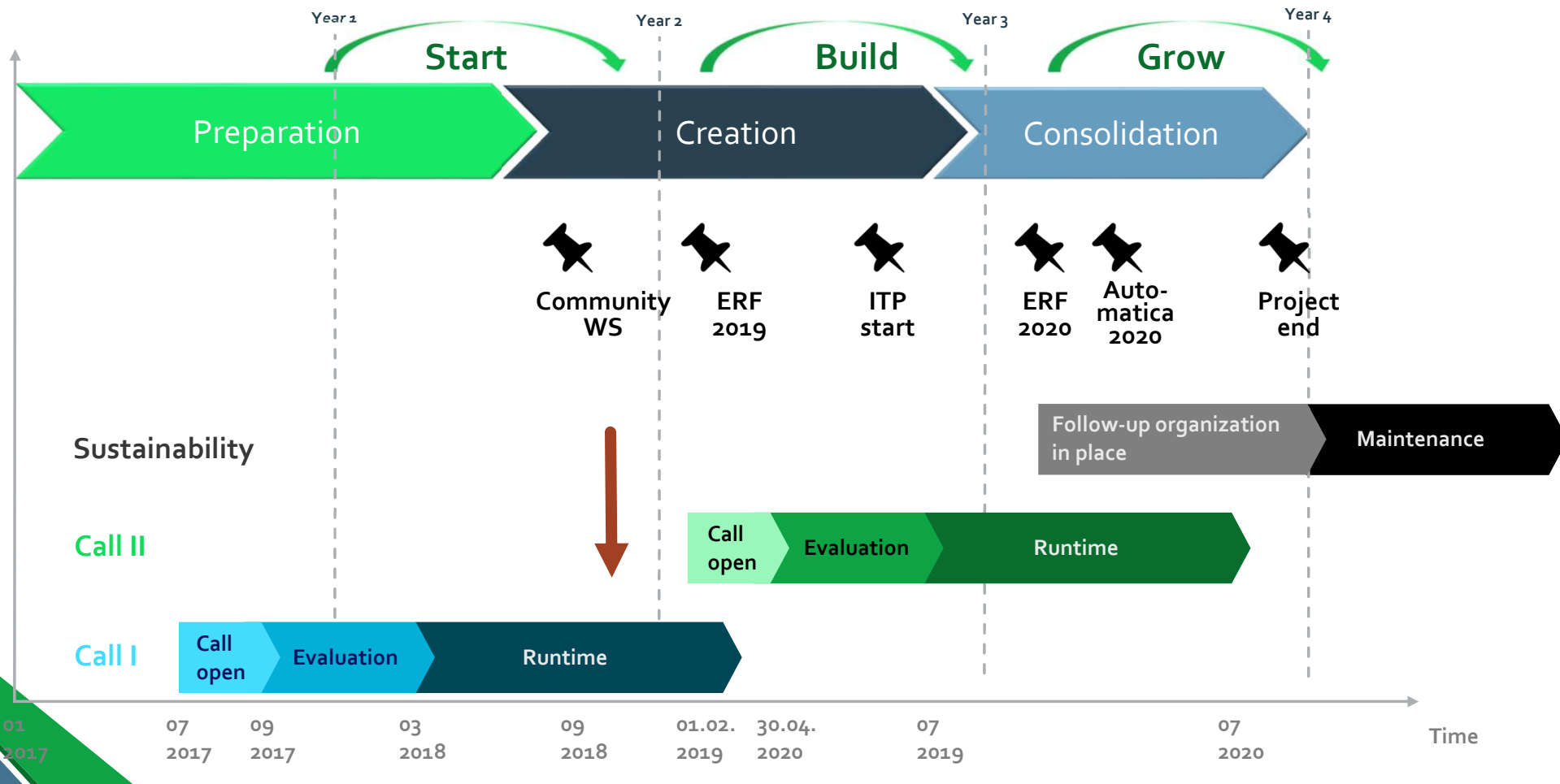


- **Core** Version of the RobMoSys **Platform**
- **First Call** for ITPs
(Integrated Technical Projects)

- RobMoSys **Pilot** Skeletons
- **Second Call** for ITPs
- **Success Stories** and
Training

- **Full** RobMoSys **Platform**
- RobMoSys **Community**
Consolidation
- Business Models and
Exploitation

Community Building Roadmap Phases



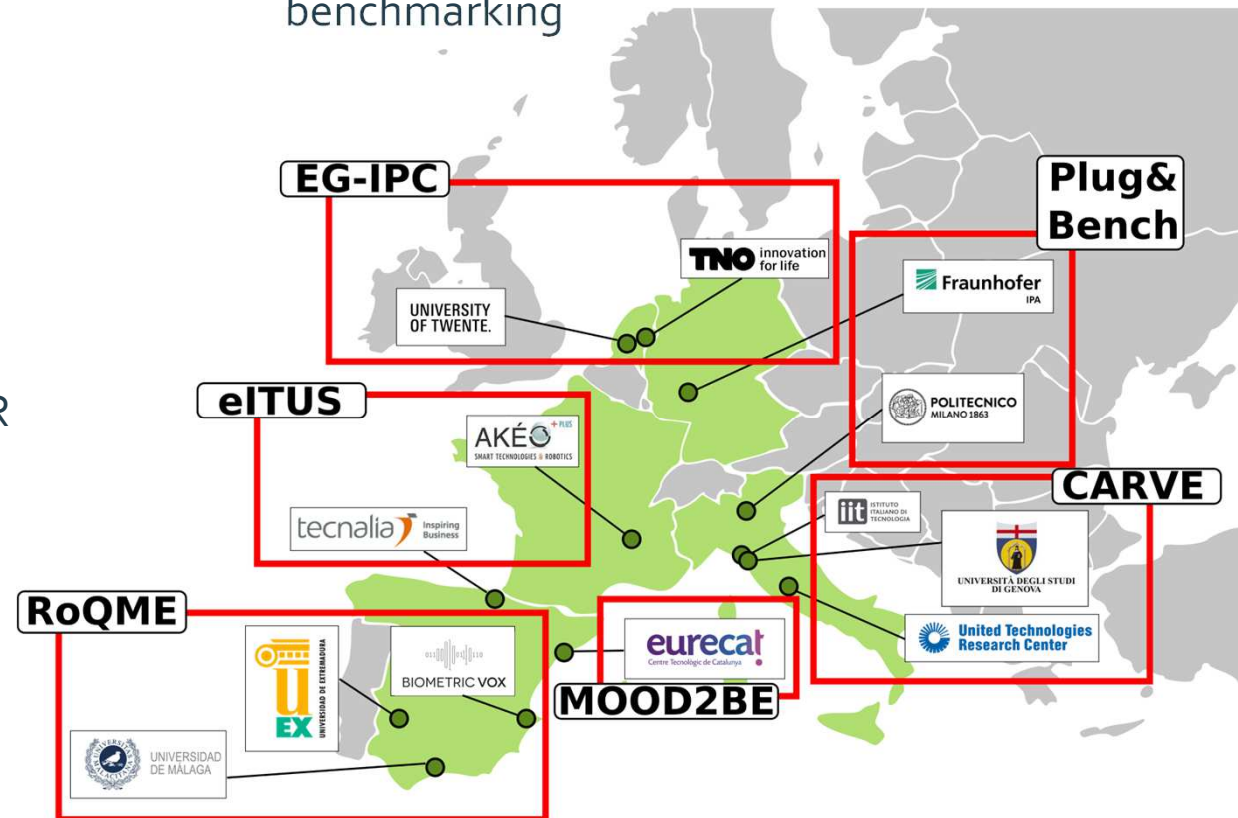
First Open Call




Better Models, Software & Tools

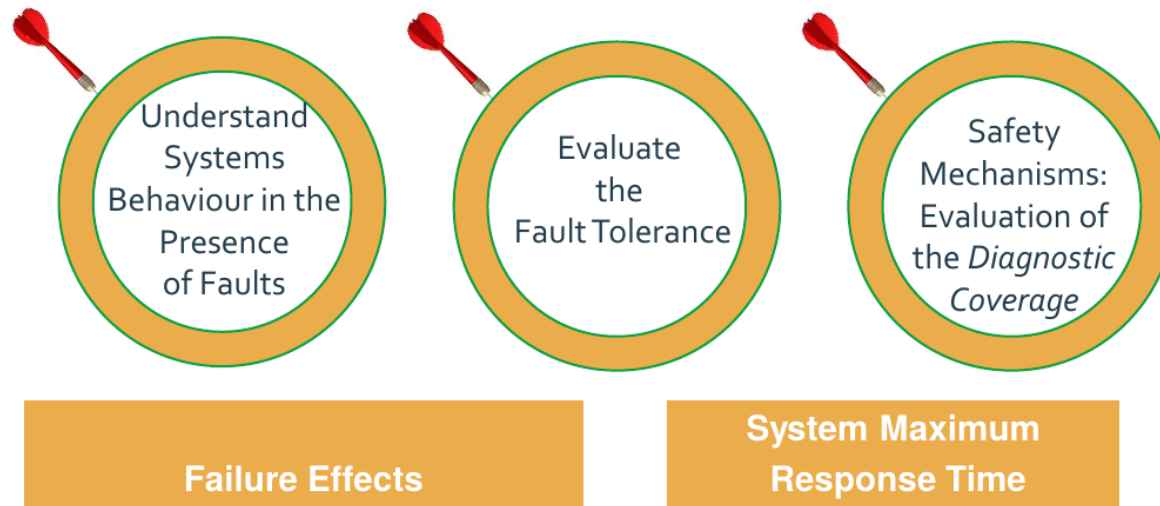
- **Funding Budget:** 1,36 Million EUR
- **Period:** Mar 2018 – Feb 2019

- **Six Selected ITPs:** focused on behaviour, communication, control, QoS, safety, benchmarking



Example of an ITP

-  **eITUS** Experimental Infrastructure Towards Ubiquitously Safe Robotic Systems using RobMoSys
- Akeo (SME) and Tecnia (research institute)
- *AIM: create an experimental infrastructure (models, software and tools) that assures system safety both at design time, using analysis and simulation-based techniques, and at run-time, using safety monitoring algorithms.*



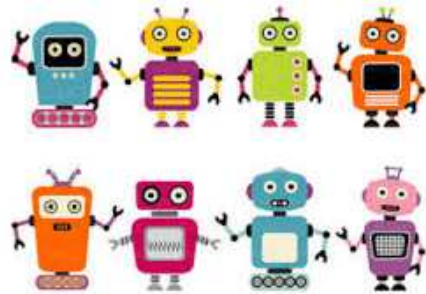
Selection criteria (from Call 1)



MoSys

1. Expected impact	Weight: 35%
<ul style="list-style-type: none">• Size of the potential users group(s)• Potential extension of the RobMoSys ecosystem coverage• Accessibility of the results, preferring open source licensing that enables composability similar to proven platform projects as Eclipse	Score: ? / 10 <i>(Threshold: 6/10)</i>
2. Technical excellence	Weight: 35%
<ul style="list-style-type: none">• Compliance with the RobMoSys meta-models and methodology• The excellence w.r.t. the state of the art in the field• Quality• Envisioned Technology Readiness Level• Clarity of suggested KPIs	Score: ? / 10 <i>(Threshold: 6/10)</i>
3. Implementation of the ITP	Weight: 30%
<ul style="list-style-type: none">• Coherence, appropriateness, effectiveness• Composition of the tandem/consortium• Risk management	Score: ? / 10 <i>(Threshold: 6/10)</i>

Second Open Call



Pilots & Success
Stories

- **Funding Budget:** 2 Million € (Pilots), 0,64 Million € (Tools)
- **Funding per ITP:** 300 K€ max.
(different project types/sizes)
- **Call Opening:** Feb 1, 2019 (- April 30th 2019)
- **Period:** Sept 2019 – Aug 2020

How to apply?

See

robmosys.eu/open-calls



Intralogistic Industry 4.0 Robot Fleet



Healthcare Assistive Robot



Flexible Assembly Cell



Modular Educational Robot



Human-Robot Collaboration for Assembly



RobMoSys Ecosystem



- RobMoSys defines a platform of assets and services to help **industry to improve their software/system engineering practice...** join us to **work together to create this ecosystem** and to demonstrate with **real industrial cases** your own **success story**.
- We call for **expert groups** which are willing to be **coached by us**, which want to help us in implementing the RobMoSys concepts under our guidance, which are ready to thereby advance the **RobMoSys way of thinking**, which are ready to go for real world examples **in line with our industrial pilots**.

Open Call II: Big Picture

Sustainability and Communication Strategy

- Key industrial communities
 - Key robotics platforms
 - Development Communities
 - Past ITPs/non selected ITPs
- Business improvements
 - Technical improvements
 - Adoption path
 - Migration path
- Instruments
 - Technical Challenges
 - Application domains
 - Sustainability roadmap
- Methodology
 - Success stories
 - Pilots
 - Tools/SW

Communities



Outlet



1. Leaflet
2. Web front-end
3. Short demo videos (user stories)

December 15th, 2018

Guidelines



1. Applicant Guide
 - Companion docs
2. Evaluation Guide

February 1, 2019

How-to



Already available for Call I
February 1, 2019 (update Call II)